

# ***HIRS Level 1 Product Format Specification***

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<i>Issue / Revision</i>	<i>Date</i>	<i>DCN. No</i>	<i>Changed Pages / Paragraphs</i>
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		ODT_DCR_232	<ul style="list-style-type: none"> <li>Section 3.5.2.4: Clarification of INSTR_DATA field:               <ul style="list-style-type: none"> <li>- integer value is signed;</li> <li>- deleted misleading Table 8 which shows raw bit format, not Level 1.</li> </ul> </li> <li>Annex: Worksheet 'Compounds', field INSTR_DATA: Corrected Type from bitst(16) to integer2.</li> </ul>
		ODT_DCR_239	<ul style="list-style-type: none"> <li>Annex: Worksheets MDR-1A &amp; MDR-1B, field ANGULAR_RELATION: Added Description note on azimuth angle range.</li> </ul>
v7E	18/10/11	Wait for OPS_ECPD_299 to be approved, then make DOCET	<ul style="list-style-type: none"> <li>Field CALIBRATION_QUALITY replaced by compound data type DATA_CALIBRATION. Annex: Updates to MDR-1A &amp; MDR-1B, and new worksheet COMPOUNDS (see Annex for full details).</li> </ul>
v7F	20/06/13	EPS_DOCET_228	<p>Changed the specifications for the 16-bit field 'CALIBRATION_QUALITY' (old section 3.5.1.13). Subdivided this into an 8-bit unsigned integer (u-byte) called 'NEDT_VALUE' and an 8-bit bit string (bitst(8)) called 'CALIBRATION_QUALITY'.</p> <p>New version of document created to maintain version continuity with previous document. Previous document 211305 given invalid document reference by DM tool.</p>

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## 1 INTRODUCTION

### 1.1 Purpose and Scope

This document is the High Resolution Infrared Radiation Sounder (HIRS/4) Level 1 Product Format Specification.

The generic product format specification used by this document is defined in the EPS Generic Product Format Specification [AD 1].

The structure and content of the products will be developed in the course of further EPS system design and nothing in this document (including the Annex) shall be taken as restricting this development of the product structures, the product or field sizes, or the time during processing at which content will be inserted into the structure of the product.

### 1.2 Structure of the Document

The document is organised in the following sections, including the introduction:

Section 1	Provides the scope of the document.
Section 2	Details the product formats for Level 1a and 1b products.
Sections 3-4	Describe the instrument and level-specific records for Level 1a and 1b products.
Section 5	details the occurrence rates of the various records within Level 1a or 1b product
Sections 6	Provides a history of version numbers for records defined within the document.
Appendix A	Provides links to detailed tables describing the record formats.

### 1.3 Applicable Documents

AD 1	EPS Generic Product Format Specification	EPS/GGS/SPE/96167
AD 2	EPS Ground Segment AVHRR/3 Level 1 Product Generation Specification	EPS/SYS/SPE/990007

### 1.4 Reference Documents

RD 1	HIRS/4 Instrument Interface Control Document	MO-IC-MMT-HI-0001
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## 2 FORMAT OF HIRS LEVEL 1 PRODUCT OVERVIEW

The product format for both HIRS Level 1a and 1b products is based on the generic product format as described in [AD 1]. This document details the instrument- and level-specific additions required for HIRS Level 1 products.

### 2.1 Generic Record Header Fields

All generic record header fields of the instrument/level specific records defined in this document shall have an INSTRUMENT\_GROUP value of HIRS [AD 1]. Level 1a Records.

### 2.2 Secondary Product Header Record

No SPHR record.

### 2.3 Global External Auxiliary Data Record

The global auxiliary datasets that are used by the Level 1a PGF (described in [AD 2]) but not written into the product are referenced by GEADRs, as specified in [AD 1].

#### 2.3.1 Record Subclasses

The following subclasses of GEADR are present for the HIRS Level 1a product.

<i>Subclass</i>	<i>Description</i>	<i>Subclass ID</i>
HIRS_CAL	Calibration and configuration parameters	1
xxxx_BIT	Land/sea/coast database	2
xxxx_TOP	Topography database	3

*Table 1: GEADR Level 1a subclasses*

### 2.4 Global Internal Auxiliary Data Record

There are two subclasses of GIADR for the Level 1a Product. These are detailed in Appendix A of this document. They contain data from static but configurable data sets.

#### 2.4.1 Record Subclasses

Record subclass determines the type of auxiliary data referenced.

<i>Subclass</i>	<i>Description</i>	<i>Subclass ID</i>
GIADR-TEMP	Temperature-radiance conversion factors	1
GIADR-ANALOG	Analogue telemetry conversion coefficients	2

*Table 2: GIADR subclasses*

GIADR-TEMP contains band correction factors used by the HIRS Level 1 processor to convert the internal warm target temperatures to radiances.

GIADR-ANALOG contains coefficients to convert analogue telemetry data to digital values. They are not used by the HIRS Level 1 processor.

Temperature-Radiance conversion constants in the GIADR are stored in ascending channel order (1, 2, 3, 4, etc.) unlike calibration terms in the MDR which are stored in the same ordering as the radiance array (1, 17, 2, 3, 13, etc.).

## 2.5 Variable External and Internal Auxiliary Data Records

There are no VEADR or VIADR records in the HIRS Level 1 products.

## 2.6 Measurement Data Record

The MDR contains the HIRS measurement data, the HIRS housekeeping telemetry data and Earth view pixel navigation and calibration data. In addition, it contains derived cloud coverage information and quality indicators. The MDR is detailed in the Annex to this document.

### 2.6.1 Record Subclasses

There is one subclass of MDR for the Level 1a product.

<i>Subclass</i>	<i>Description</i>	<i>Subclass ID</i>
MDR-1A	Level 1A MDR	1

*Table 3: MDR Level 1a subclasses*

### 2.6.2 MDR Fields

#### 2.6.2.1 *QUALITY\_INDICATOR*

<i>Bit</i>	<i>Meaning</i>
31	Do not use scan for dataset generation
30	Time sequence error detected with this scan (see below)
29	Data gap precedes this scan
28	No calibration (see below)
27	No earth location (see below)
26	First good time following a clock update
25	Instrument status changed with this scan
24	Line incomplete, pixels missing
23-0	Not used

*Table 4: QUALITY\_INDICATOR bit string definitions*



**2.6.2.2 SCAN\_LINE\_QUALITY**

<i>Bit</i>	<i>Meaning</i>
	<b>Time Problem Code</b> (all bits off implies the scan time is as expected)
31 – 24	Not used
23	Time field is bad but can probably be inferred from the previous good time
22	Time field is bad and can't be inferred from the previous good time
21	This record starts a sequence that is inconsistent with previous times (i.e., there is a time discontinuity). This may or may not be associated with a spacecraft clock update (See bit 26 in QUALITY_INDICATOR Field)
20	Start of a sequence that apparently repeats scan times that have been previously accepted
19 – 16	Not used
	<b>Calibration Code Problem</b> Note: These bits complement the channel indicators; for normal calibration all bits are set to 0.
15	Scan line was not calibrated because of bad time
14	Scan line was calibrated using fewer than the preferred number of scan lines because of proximity to start or end of data set or to a data gap
13	Scan line was not calibrated because of bad or insufficient PRT data
12	Scan line was calibrated but with marginal PRT data
11	Some uncalibrated channels on this scan. (See channel indicators.)
10	Uncalibrated due to instrument mode.
9	Questionable calibration because of antenna position error of space view
8	Questionable calibration because of antenna position error of black body
	<b>Earth Location Problem Code</b> (all bits off indicates the Earth location was normal)
7	Not earth located because of bad time; earth location fields zero filled
6	Earth location questionable because of questionable time code. (See time problem flags above.)
5	Earth location questionable – only marginal agreement with reasonableness check.
4	Earth location questionable – fails reasonableness check
3	Earth location questionable because of antenna position check
2 – 0	Not used

*Table 5: SCAN\_LINE\_QUALITY bit string definitions*

### 2.6.2.3 DATA\_CALIBRATION

This is a compound data type. For each channel, it contains information about the actual value of the NEdN and the calibration quality:

<i>Field</i>	<i>Description</i>	<i>SF</i>	<i>Dimension</i>	<i>Type</i>	<i>Type Size</i>	<i>Field Size</i>
NEDN_VALUE	Value of the noise equivalent channel radiance	11 for Channel 1: 2 for Channel 2-12 4 for Channel 13-19	1, 1, 1	u-byte	1	1
CALIBRATION_QUALITY	Channel Quality Flags	0	1, 1, 1	bitst(8)	1	1

Table 6: Structure of compound data type DATA\_CALIBRATION

The content of the individual fields is defined below:

#### 2.6.2.3.1 NEDN\_VALUE

**Type:** u-byte

Channel-dependent value of NEdN; the following scaling factors (SF) and limits are to be used:

<i>Channel</i>	<i>SF</i>	<i>Limits</i>
Channel 1	1	values corresponding to NEdNs larger than 25.5 K will be set to 255
Channels 2 to 12	2	values corresponding to NEdNs larger than 2.55 K will be set to 255
Channels 13 to 19	4	values corresponding to NEdNs larger than 0.0255 K will be set to 255
Channel 20	3	values corresponding to a dark current noise larger than 0.255 will be set to 255

NEdN and NEdT specifications:

<i>Channel</i>	<i>Limits</i>
Channel 1	3.0 mW/(m <sup>2</sup> sr cm <sup>-1</sup> ) or 1.792 K
Channel 2	0.67 mW/(m <sup>2</sup> sr cm <sup>-1</sup> ) or 0.397 K
Channel 3	0.50 mW/(m <sup>2</sup> sr cm <sup>-1</sup> ) or 0.294 K
Channel 4	0.31 mW/(m <sup>2</sup> sr cm <sup>-1</sup> ) or 0.181 K
Channel 5:	0.21 mW/(m <sup>2</sup> sr cm <sup>-1</sup> ) or 0.122 K
Channel 6	0.24 mW/(m <sup>2</sup> sr cm <sup>-1</sup> ) or 0.138 K
Channel 7	0.20 mW/(m <sup>2</sup> sr cm <sup>-1</sup> ) or 0.115 K
Channel 8	0.10 mW/(m <sup>2</sup> sr cm <sup>-1</sup> ) or 0.583 × 10 <sup>-1</sup> K
Channel 9	0.15 mW/(m <sup>2</sup> sr cm <sup>-1</sup> ) or 0.963 × 10 <sup>-1</sup> K
Channel 10	0.15 mW/(m <sup>2</sup> sr cm <sup>-1</sup> ) or 0.854 × 10 <sup>-1</sup> K
Channel 11	0.20 mW/(m <sup>2</sup> sr cm <sup>-1</sup> ) or 0.209 K
Channel 12	0.20 mW/(m <sup>2</sup> sr cm <sup>-1</sup> ) or 0.295 K

<i>Channel</i>	<i>Limits</i>
Channel 13	0.006 mW/(m <sup>2</sup> sr cm <sup>-1</sup> ) or $0.500 \times 10^{-1}$ K
Channel 14	0.003 mW/(m <sup>2</sup> sr cm <sup>-1</sup> ) or $0.265 \times 10^{-1}$ K
Channel 15	0.004 mW/(m <sup>2</sup> sr cm <sup>-1</sup> ) or $0.385 \times 10^{-1}$ K
Channel 16	0.004 mW/(m <sup>2</sup> sr cm <sup>-1</sup> ) or $0.392 \times 10^{-1}$ K
Channel 17	0.002 mW/(m <sup>2</sup> sr cm <sup>-1</sup> ) or $0.333 \times 10^{-1}$ K
Channel 18	0.002 mW/(m <sup>2</sup> sr cm <sup>-1</sup> ) or $0.455 \times 10^{-1}$ K
Channel 19	0.001 mW/(m <sup>2</sup> sr cm <sup>-1</sup> ) or $0.370 \times 10^{-1}$ K
Channel 20	N/A

### 2.6.2.3.2 CALIBRATION\_QUALITY

**Type:** bitst(8). All bits off implies a good calibration.

<i>Bit</i>	<i>Meaning</i>
7	Actual NEdN value exceeds specification
6	Actual NEdN value exceeds 95 % of specification
5	No good black body counts for scan line
4	No good space view counts for scan line
3	No good PRTs for this line
2	Marginal black body counts for this line
1	Marginal space view counts for this line
0	Marginal PRT temperatures for this line

Table 7: CALIBRATION\_QUALITY bit string definitions

### 2.6.2.4 DATA\_ELEM\_COUNT

This is a compound data type. Please refer to [AD 1], section 3.3.3.2, for further details.

<i>Field</i>	<i>Description</i>	<i>SF</i>	<i>Dimension</i>	<i>Type</i>	<i>Type Size</i>	<i>Field Size</i>
DATA_ELEM_HEAD	Header of DATA_ELEM	0	1, 1, 1	bitst(32)	4	4
INSTR_DATA	20 array elements containing HIRS counts per channel	0	20, 1, 1	bitst(16)	2	40

DATA\_ELEM\_HEAD is a bit string with components as defined below:

<i>Bit</i>	<i>Meaning</i>
31 - 24	Scan Encoder Position (0 to 199)
23 - 19	Electronic Cal Level Indicator (0 to 31)
18 - 17	Not used
16	1 = Valid data, 0 = Ignore radiometric data
15	Odd Bit Parity
14 - 13	Not used
12 - 7	Channel 1 Period Monitor (0 – 63)
6 – 1	Element Number (0 – 63)
0	Filter Sync Designator (= 1 if the filter wheel is in sync with timing system)

*Table 8: Data Element Header bit string definitions*

This corresponds to the two first 13-bit words in the 288-bit element [RD 1].

For DIGITAL\_A\_DATA\_ELEMENT\_COUNT 0 to 55 the INSTR\_DATA field contains the 20 channel values of the scan pixel with Element Number 0 to 55 respectively.

The 13-bit integer counts with the non-standard sign bit are converted to the equivalent 16-bit signed integer value as specified in the GPFS [AD 1] and the HIRS FOV counts scaled to the correct 0-8191 counts range [RD 1].

The sequence of the 20 channel values for each scan pixel begins with channel 1 and is followed by this channel sequence: 17, 2, 3, 13, 4, 18, 11, 19, 7, 8, 20, 10, 14, 6, 5, 15, 12, 16, 9.

#### **2.6.2.5 DATA\_ELEM\_FLAG**

This is a compound data type.

Please refer to [RD 1], section 3.3.3.2, for further details.

<i>Field</i>	<i>Description</i>	<i>SF</i>	<i>Dimension</i>	<i>Type</i>	<i>Type Size</i>	<i>Field Size</i>
DATA_ELEM_HEAD	Header of DATA_ELEM as per DATA_ELEM_COUNTS	0	1, 1, 1	bitst(32)	4	4
FLAG_DATA	20 array elements containing data flags	0	20, 1, 1	bitst(16)	2	40

For DIGITAL\_A\_DATA\_ELEMENT\_COUNT 56 to 63 the FLAG\_DATA fields contain HIRS instrument status information as detailed in [RD 1], figure 3.3.3.2/1.

### 2.6.2.6 DATA\_ELEM\_RADIANCES

This is a compound data type. Please refer to [RD 1], section 3.3.3.2, for further details.

<i>Field</i>	<i>Description</i>	<i>SF</i>	<i>Dimension</i>	<i>Type</i>	<i>Type Size</i>	<i>Field Size</i>
DATA_ELEM_HEAD	Header of DATA_ELEM as per DATA_ELEM_COUNTS	0	1, 1, 1	bitst(32)	4	4
RAD_DATA	20 instrument data	7	20, 1, 1	integer4	4	80

For DIGITAL\_A\_DATA\_ELEMENT\_RAD 0 to 55 the INSTR\_DATA field contains the 20 radiance values of the scan pixel with Element Number 0 to 55 respectively.

The sequence of the 20 channel values for each scan pixel is channel 1 followed by the channels 17, 2, 3, 13, 4, 18, 11, 19, 7, 8, 20, 10, 14, 6, 5, 15, 12, 16, 9.

If a cold target scan is performed (although possible in theory, this is not expected to occur in practice) then the radiances are not derived so default dummy values (as per GPFS [AD 1]) are placed in the INSTR\_DATA field.

### 2.6.2.7 INSTRUMENT\_INVALID\_DIGITAL\_WORD\_FLAG

If bit = 1, associated telemetry bit was not recently updated (for NOAA satellites this means not updated during most recent minor frame cycle). This is possibly due to lost data. This information is derived by the HIRS level 1 processor.

<i>Bit</i>	<i>Meaning</i>
15	Instrument power
14	Electronics power
13	Filter motor power
12	Scan motor power
11	Cooler heater
10	Filter housing heater
9	Cooler door release
8	Cooler window heater
7	Go to nadir position
6	Calibration sequence
5	Cooler door closed
4	Cooler door fully open
3	Filter motor power level
2	Patch temperature controller
1-0	Not used

Table 9: INSTRUMENT\_INVALID\_DIGITAL\_WORD\_FLAG bit string definitions

**2.6.2.8 DIGITAL\_B\_DATA**

<i>Bit</i>	<i>Meaning</i>
15	Instrument power (0=off; 1=on)
14	Electronics power (0=off; 1=on)
13	Filter motor power (0=off; 1=on)
12	Scan motor power (0=off; 1=on)
11	Cooler heater (0=off; 1=on)
10	Filter housing heater (0=off; 1=on)
9	Cooler door release (0=disabled; 1=enabled)
8	Cooler window heater (0=on; 1=off)
7	Go to nadir position (0=no; 1=yes/initiated)
6	Calibration sequence (0=disabled; 1=enabled)
5	Cooler door closed (0=yes; 1=no)
4	Cooler door fully open (0=yes; 1=no)
3	Filter motor power level (0=normal; 1=high)
2	Patch temperature controller (0=off; 1=on)
1-0	Not used

*Table 10: DIGITAL\_B\_DATA bit string definitions*
**2.6.2.9 INSTRUMENT\_INVALID\_ANALOG\_WORD\_FLAG**

<i>Bit</i>	<i>Meaning</i>
31-17	Not used
16	Patch controller power (following word 16)
15-2	Following words 15 through 2 ( in order )
1	Radiator temperature (following word 1)
0	Not used

*Table 11: INSTRUMENT\_INVALID\_ANALOG\_WORD\_FLAG bit string definitions*

**2.6.2.10 ANALOG\_DATA**

<b>Word</b>	<b>Meaning</b>
1	Radiator Temperature
2	Base Plate Temperature
3	Electronics Temperature
4	Patch Temperature
5	Filter Housing Controller Current
6	Scan Motor Temperature
7	Filter Wheel Motor Temperature
8	+5 VDC Monitor
9	+10 VDC TLM/DC/DC/Conv.
10	+7.5 VDC TLM/DC/DC/Conv.
11	-7.5 VDC TLM/DC/DC/Conv.
12	+15 VDC Monitor
13	-15 VDC Monitor
14	Filter Wheel Motor Current
15	Scan Motor Current
16	Patch Controller Power

*Table 12: ANALOG DATA words*

### 2.6.2.11 NAVIGATION\_STATUS

<i>Bit</i>	<i>Meaning</i>
31 – 17	Not used
16	Earth location corrected for Euler angles
15 – 12	Earth location indicator 0 = earth location available 1 = user ephemeris files older than 24 hours 2 = no earth location available
11 – 8	Spacecraft attitude control 0 = operating in YGC or NOMINAL mode 1 = operating in another mode 2 = attitude exceeds nominal tolerance
7 – 4	Attitude SMODE 0 = NOMINAL mode 1 = rate nulling mode 2 = YGC mode 3 = search mode 4 = coast mode
3 – 0	Attitude mode 0 = NOMINAL mode/no test 1 = yaw axis test in progress 2 = roll axis test in progress 3 = pitch axis test in progress

*Table 13: NAVIGATION\_STATUS bit string definitions*

### 2.6.2.12 Calibration Coefficients

The instantaneous calibration coefficients shall be put into MDR-1A and MDR-1B for the Cold Space and Warm target scan lines (and also for the Cold Target which, although possible in theory, should not occur in normal practice). The calculated interpolated coefficients shall be stored for each Earth scan line.



### 3 LEVEL 1B RECORDS

The structure of the Level 1b records is mostly identical to those of Level 1a. Record differences for GEADR and MDR are given below.

The only difference for Level 1b data is that the Earth pixel counts are calibrated to radiances for the channels 1 to 19 and reflectance factors for the channel 20.

#### 3.1 Global External Auxiliary Data Record

##### 3.1.1 Record Subclasses

The following subclasses of GEADR are present for the HIRS Level 1b product.

<i>Subclass</i>	<i>Description</i>	<i>Subclass ID</i>
HIRS_CAL	Calibration and configuration parameters	1

*Table 14: GEADR Level 1b subclasses*

#### 3.2 Measurement Data Record

See also Section 2.6 for more details of the MDR record and fields.

##### 3.2.1 Record Subclasses

There is one subclass of MDR for the Level 1b product.

<i>Subclass</i>	<i>Description</i>	<i>Subclass ID</i>
MDR-1B	Level 1B MDR	2

*Table 15: MDR Level 1b subclasses*

## 4 RECORD OCCURRENCE INFORMATION

### 4.1 Level 1a

<i>Record</i>	<i>Occurrence</i>
MPHR	Once per product
GIADR-TEMP	Once per product
GIADR-ANALOG	Once per product
MDR-1A	Once per scan

*Table 16: Level 1a records occurrence rates*

### 4.2 Level 1b

<i>Record</i>	<i>Occurrence</i>
MPHR	Once per product
GIADR-TEMP	Once per product
GIADR-ANALOG	Once per product
MDR-1B	Once per scan

*Table 17: Level 1b records occurrence rates*

## 5 RECORD FORMAT VERSION CONTROL

This section provides version numbers for the records defined within this document.

<i>Record Subclass</i>	<i>Format Version Number</i>	<i>Issue Defined</i>
<b>GIADR-ANALOG</b>	<b>2</b>	<b>6.3</b>
	1	6.2 (CDR)
<b>GIADR-TEMP</b>	<b>2</b>	<b>6.3</b>
	1	6.2 (CDR)
<b>MDR-1A</b>	<b>3</b>	<b>7E</b>
	2	6.3
	1	6.2 (CDR)
<b>MDR-1B</b>	<b>3</b>	<b>7E</b>
	2	6.3
	1	6.2 (CDR)

*Table 18: Record Format Version Numbers*

## **APPENDIX A      DETAILED SPECIFICATION OF HIRS LEVEL 1 DATA RECORDS**

In the following Annex, detailed format specifications for all the Variable Internal and Measurement Data Records in HIRS Level 1 products are included:

- GIADR-ANALOG
- GIADR-TEMP
- MDR-1A
- MDR-1B

The Annex is accessible under Document Reference: EPS.MIS.SPE.97230.ANX .

<b>This Document</b>	
<b>Title</b>	HIRS/4 LEVEL 1 PRODUCT FORMAT SPECIFICATION TABLES
<b>Reference Number</b>	EPS/MIS/SPE/97230
<b>Change Record</b>	
<b>Issue 4 Draft A Rev 1</b>	Removed Detailed Navigation section from SPHR-1A
	Corrected 90 'points' in ADR-1A to 56 FsOV for ANGULAR_RELATION, EARTH_LOCATION, SURFACE_PROPERTY, and TERRAIN_ELEVATION, changed CALIBRATION_QUALITY to reflect 20 rather than 15 entities (because there are 20 HIRS channels)
<b>Issue 4 Draft B</b>	Updated tables to match updated GPFS document
	Changed CLOUD_INFORMATION in ADR-1A and 1B to PERCENTAGE_CLEAR_SKY
	Update REC_HEAD size from 12 to 24 bytes in TYPES worksheet
	Make SPHR an ASCII record
	Moved INSTRUMENT_STATUS fields from SPHR to VIADR
	Removed INSTRUMENT_STATUS_RECORD_CHANGE from VIADR-1a
	Made SPHR-1A, GIADR-1A (all types), VIADR-1a (all types) applicable to Level 1b product as well
<b>Revision</b>	
<b>Issue 5 Revision 0</b>	Issue for CGS PDR
<b>Issue 5 Revision 1</b>	Revised Issue for CGS PDR
<b>Issue 5 Revision 2</b>	Moved contents of ADR into MDR-1A and MDR-1B records
	Removed Instrument Status information from SPHR as this is contained in VIADR-INSTATE and is not global information (it may change in a product)
<b>Issue 6 Revision 0</b>	Removed ADRs. Moved ADR contents to relevant MDR
	Added DEGRADED_INST_MDR and DEGRADED_PROC_MDR flags to MDRs
<b>Issue 6 Revision 1</b>	Complete reorganisation
<b>Issue 6 Revision 2</b>	Removed SPHR
	Removed OBT/UTC Correction Information from MDR-1A and MDR-1B
<b>Issue 6 Revision 3</b>	<b>EUM.EPS.SYS.DCR.02.169</b>
	EARTH_LOCATION field in MDRs. Changed field type to integer4 and scale factor to 4
	MDRs: INSTRUMENT_INVALID_ANALOG_WORD flag field type changed to bitst(32) consistent with main text
	CALIBRATION_QUALITY field size changed to 20 to make flag per channel
	GIADR-TEMP: TEMPERATURE_RADIANCE_CENTRAL_WAVELENGTH, TEMPERATURE_RADIANCE_CONSTANTB, TEMPERATURE_RADIANCE_CONSTANTC field data types changed from integer2 to integer4 in order to hold necessary data
	GIADR-ANALOG: C2 coefficients scale factor changed to 10^2

	Change TIME_ATTITUDE and SPACECRAFT_ATTITUDE fields to unsigned field types
	Correct SPACECRAFT_+ATTITUDE field name to SPACECRAFT_ALTITUDE
	Correct scale factor for MDR.ANGULAR_RELATIONS from 3 to 2
	EULER_ANGLE data type changed to integer2 and scale factor changed to 3
	Break DATA_ELEM compound into more homogeneous parts. Split DIGITAL_A_DATA_ELEMENT field into three components with postfixes _COUNT, _FLAF, _RAD for counts, flags and radiances.
	GIADR-TEMP: ALBEDO_RADIANCE_SOLAR_IRRADIANCE and ALBEDO_RADIANCE_EQUIVALENT_WIDTH TBD for units replaced with values.
	<b>EUM.EPS.SYS.DCR.03.044</b>
	GIADR-TEMP.TEMPERATURE_RADIANCE_CENTRAL_WAVENUMBER split scale factor. SF = 6 for ch 1 to 12 and 5 for ch 13 to 19
	GIADR-ANALOG: Clarified scale factor column and corrected units for coefficients
<b>Issue 6 Revision 4</b>	<b>EUM.EPS.SYS.DCR.04.015</b>
	GIADR-TEMP: Clarified ordering of channel indexed arrays
	COMPOUNDS: Copied compound structures into Annex for compatability with other PFSs
	MDR-1A/1B: added reference to Section 3.5.1.12
	GIADR-ANALOG: Corrected record name from GIADR-ANALOG-1A to GIADR-ANALOG consistent with main text
<b>Issue 6 Revision 5</b>	<b>EUM.EPS.SYS.DCR.05.0210</b>
	COMPOUNDS
	DATA_ELEM_FLAG.INSTR_DATA - corrected name to DATA_ELEM_FLAG.FLAG_DATA consistent with Section 3.5.1.5
	DATA_ELEM_RADIANCES.INSTR_DATA - corrected name to DATA_ELEM_RADIANCES.RAD_DATA consistent with Section 3.5.1.6
	Added Scale factor 7 for field DATA_ELEM_RADIANCES.RAD_DATA
	Added units for field DATA_ELEM_RADIANCES.RAD_DATA
	Corrected type for field DATA_ELEM_RADIANCES.RAD_DATA to integer4 from bitst(16) consistent with Section 3.5.1.6 and updated type size and field size accordingly
<b>Version 7A 18/07/08</b>	Migrated into Hummingbird. Contents identical with issue 6.5.
<b>Version 7B 08/09/08</b>	No changes to annex.
<b>Version 7C 30/01/09</b>	No changes to annex.
<b>Version 7D 22/02/11</b>	<b>ODT_DCR_232</b>
	COMPOUNDS: Update for documentation error:
	DATA_ELEM_COUNT.INSTR_DATA - Corrected Type from bitst(16) to integer2 (consistent with Section 3.5.2.4).

	<b>ODT_DCR_239</b>
	MDR-1A & MDR-1B, field ANGULAR_RELATION: Added Description note on azimuth angle range.
<b>Version 7E 18/10/11</b>	<b>TBD</b>
	New worksheet to describe compound data type DATA_CALQUAL. Also added to Types sheet. MDR-1A & MDR-1B: Field CALIBRATION_QUALITY replaced by DATA_CALIBRATION.

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Worksheet: Compounds

DATA_ELEM_COUNT									
FIELD	DESCRIPTION	SF	UNITS	DIM1	DIM2	DIM3	TYPE	TYPE SIZE	FIELD SIZE
DATA_ELEM_HEAD	Header of DATA_ELEM	NA	NA	1	1	1	bitst(32)	4	4
INSTR_DATA	20 array elements containing HIRS counts per channel	NA	NA	20	1	1	integer2	2	40

DATA_ELEM_FLAG									
FIELD	DESCRIPTION	SF	UNITS	DIM1	DIM2	DIM3	TYPE	TYPE SIZE	FIELD SIZE
DATA_ELEM_HEAD	Header of DATA_ELEM	NA	NA	1	1	1	bitst(32)	4	4
FLAG_DATA	20 array elements containing data flags	NA	NA	20	1	1	bitst(16)	2	40

DATA_ELEM_RADIANCES									
FIELD	DESCRIPTION	SF	UNITS	DIM1	DIM2	DIM3	TYPE	TYPE SIZE	FIELD SIZE
DATA_ELEM_HEAD	Header of DATA_ELEM	NA	NA	1	1	1	bitst(32)	4	4
RAD_DATA	20 instrument data	7	Ch 1 - 19 mW/(m <sup>2</sup> .sr.cm) Ch 20 Percentage Reflectance	20	1	1	integer4	4	80

DATA_CALQUAL									
FIELD	DESCRIPTION	SF	UNITS	DIM1	DIM2	DIM3	TYPE	TYPE SIZE	FIELD SIZE
NEDN_VALUE	Value of the noise equivalent radiance	1 for Ch. 1; 2 for Ch. 2 to 12; 4 for Ch. 13 to 19	mW/(m <sup>2</sup> sr cm <sup>-1</sup> )	1	1	1	u-byte	1	1
CALIBRATION_QUALITY	Channel Quality Flags	0	N/A	1	1	1	bitst(8)	1	1



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Worksheet: GIADR-TEMP

FIELD	DESCRIPTION	SF	UNITS	DIM1	DIM2	DIM3	TYPE	TYPE SIZE	FIELD SIZE	OFFSET
RECORD_HEADER	Generic Record Header	0		1	1	1	REC_HEAD	20	20	0
<b>TEMPERATURE-SENSOR CONVERSION</b>										
TEMPERATURE_RADIANCE_CENTRAL_WAVENUMBER	Temperature-Radiance Central Wavenumber $n_c$ (ch. 1-19). Scale Factor is: 6 for ch 1 - 12 5 for ch 13 - 19 (ch 1 - 19 in order)	See Descrip.	cm <sup>-1</sup>	19	1	1	integer4	4	76	20
TEMPERATURE_RADIANCE_CONSTANTB	Temperature-Radiance Constant Intercept b (ch 1 - 19 in order)	6	K	19	1	1	integer4	4	76	96
TEMPERATURE_RADIANCE_CONSTANTC	Temperature-Radiance Constant Slope c - (ch 1 - 19 in order)	6	K/K	19	1	1	integer4	4	76	172
ALBEDO_RADIANCE_SOLAR_IRRADIANCE	Albedo-Radiance Ch 20 Solar Filtered Irradiance	6	W/m <sup>2</sup>	1	1	1	integer2	2	2	248
ALBEDO_RADIANCE_EQUIVALENT_WIDTH	Albedo-Radiance Ch 20 Equivalent Filter Width	6	cm <sup>-1</sup>	1	1	1	integer2	2	2	250
<b>Size of the record</b>										252

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 Worksheet: GIADR-ANALOG

FIELD	DESCRIPTION	SF	UNITS	DIM1	DIM2	DIM3	TYPE	TYPE SIZE	FIELD SIZE	OFFSET
RECORD_HEADER	Generic Record Header	0		1	1	1	REC_HEAD	20	20	0
<b>AD CONVERSION</b>										
<i>Analog telemetry conversion</i>										
RADIATOR_TEMPERATURE_COEFFICIENT	Radiator Temperature Coefficients (c <sub>0</sub> -c <sub>5</sub> )	c0=2 c1=2 c2=3 c3=3 c4=3 c5=5	c0=K c1=K/cnt c2=K/cnt^2 c3=K/cnt^3 c4=K/cnt^4 c5=K/cnt^5	6	1	1	integer2	2	12	20
BASEPLATE_TEMPERATURE_COEFFICIENT	Base Plate Temperature Coefficients (c <sub>0</sub> -c <sub>5</sub> )	c0=2 c1=2 c2=3 c3=3 c4=3 c5=5	c0=K c1=K/cnt c2=K/cnt^2 c3=K/cnt^3 c4=K/cnt^4 c5=K/cnt^5	6	1	1	integer2	2	12	32
ELECTRONIC_TEMPERATURE_COEFFICIENT	Electronics Temperature Coefficients (c <sub>0</sub> -c <sub>5</sub> )	c0=2 c1=2 c2=3 c3=3 c4=3 c5=5	c0=K c1=K/cnt c2=K/cnt^2 c3=K/cnt^3 c4=K/cnt^4 c5=K/cnt^5	6	1	1	integer2	2	12	44
PATCH_TEMPERATURE_COEFFICIENT	Patch Temperature Coefficients (c <sub>0</sub> -c <sub>5</sub> )	c0=2 c1=2 c2=3 c3=3 c4=3 c5=5	c0=K c1=K/cnt c2=K/cnt^2 c3=K/cnt^3 c4=K/cnt^4 c5=K/cnt^5	6	1	1	integer2	2	12	56
FILTER_HOUSING_CONTROLLER_CURRENT_COEFFICIENT	Filter Housing Controller Current Coefficients (c <sub>0</sub> -c <sub>5</sub> )	c0=2 c1=2 c2=3 c3=3 c4=3 c5=5	c0=K c1=K/cnt c2=K/cnt^2 c3=K/cnt^3 c4=K/cnt^4 c5=K/cnt^5	6	1	1	integer2	2	12	68

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<b>SCAN_MOTOR_TEMPERATURE_COEFFICIENT</b>	<b>Scan Motor Temperature Coefficients (c<sub>0</sub>-c<sub>5</sub>)</b>	c0=2 c1=2 c2=3 c3=3 c4=3 c5=5	c0=K c1=K/cnt c2=K/cnt^2 c3=K/cnt^3 c4=K/cnt^4 c5=K/cnt^5	6	1	1	integer2	2	12	80
<b>FILTER_WHEEL_MOTOR_TEMPERATURE_COEFFICIENT</b>	<b>Filter Wheel Motor Temperature Coefficients (c<sub>0</sub>-c<sub>5</sub>)</b>	c0=2 c1=2 c2=3 c3=3 c4=3 c5=5	c0=K c1=K/cnt c2=K/cnt^2 c3=K/cnt^3 c4=K/cnt^4 c5=K/cnt^5	6	1	1	integer2	2	12	92
<b>PLUS5_VDC_MONITOR_COEFFICIENT</b>	<b>+5 VDC Monitor Coefficients (c<sub>0</sub>-c<sub>5</sub>)</b>	c0=2 c1=2 c2=3 c3=3 c4=3 c5=5	c0=V c1=V/cnt c2=V/cnt^2 c3=V/cnt^3 c4=V/cnt^4 c5=V/cnt^5	6	1	1	integer2	2	12	104
<b>PLUS10_VDC_TMLDC_COEFFICIENT</b>	<b>+10 VDC TLM/DC/DC Coefficients (c<sub>0</sub>-c<sub>5</sub>)</b>	c0=2 c1=2 c2=3 c3=3 c4=3 c5=5	c0=V c1=V/cnt c2=V/cnt^2 c3=V/cnt^3 c4=V/cnt^4 c5=V/cnt^5	6	1	1	integer2	2	12	116
<b>PLUS75_VDC_TMLDC_COEFFICIENT</b>	<b>+7.5 VDC TLM/DC/DC Coefficients (c<sub>0</sub>-c<sub>5</sub>)</b>	c0=2 c1=2 c2=3 c3=3 c4=3 c5=5	c0=V c1=V/cnt c2=V/cnt^2 c3=V/cnt^3 c4=V/cnt^4 c5=V/cnt^5	6	1	1	integer2	2	12	128
<b>MINUS75_VDC_TMLDC_COEFFICIENT</b>	<b>-7.5 VDC TLM/DC/DC Coefficients (c<sub>0</sub>-c<sub>5</sub>)</b>	c0=2 c1=2 c2=3 c3=3 c4=3 c5=5	c0=V c1=V/cnt c2=V/cnt^2 c3=V/cnt^3 c4=V/cnt^4 c5=V/cnt^5	6	1	1	integer2	2	12	140

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<b>PLUS15_VDC_MONITOR_COEFFICIENT</b>	<b>+15 VDC Monitor Coefficients (c<sub>0</sub>-c<sub>5</sub>)</b>	c0=2 c1=2 c2=3 c3=3 c4=3 c5=5	c0=V c1=V/cnt c2=V/cnt <sup>2</sup> c3=V/cnt <sup>3</sup> c4=V/cnt <sup>4</sup> c5=V/cnt <sup>5</sup>	6	1	1	integer2	2	12	152
<b>MINUS15_VDC_MONITOR_COEFFICIENT</b>	<b>-15 VDC Monitor Coefficients (c<sub>0</sub>-c<sub>5</sub>)</b>	c0=2 c1=2 c2=3 c3=3 c4=3 c5=5	c0=V c1=V/cnt c2=V/cnt <sup>2</sup> c3=V/cnt <sup>3</sup> c4=V/cnt <sup>4</sup> c5=V/cnt <sup>5</sup>	6	1	1	integer2	2	12	164
<b>FILTER_WHEEL_MOTOR_CURRENT_COEFFICIENT</b>	<b>Filter Wheel Motor Current Coefficients (c<sub>0</sub>-c<sub>5</sub>)</b>	c0=2 c1=2 c2=3 c3=3 c4=3 c5=5	c0=A c1=A/cnt c2=A/cnt <sup>2</sup> c3=A/cnt <sup>3</sup> c4=A/cnt <sup>4</sup> c5=A/cnt <sup>5</sup>	6	1	1	integer2	2	12	176
<b>SCAN_MOTOR_CURRENT_COEFFICIENT</b>	<b>Scan Motor Current Coefficients (c<sub>0</sub>-c<sub>5</sub>)</b>	c0=2 c1=2 c2=3 c3=3 c4=3 c5=5	c0=A c1=A/cnt c2=A/cnt <sup>2</sup> c3=A/cnt <sup>3</sup> c4=A/cnt <sup>4</sup> c5=A/cnt <sup>5</sup>	6	1	1	integer2	2	12	188
<b>PATCH_CONTROLLER_POWER_COEFFICIENT</b>	<b>Patch Controller Power Coefficients (c<sub>0</sub>-c<sub>5</sub>)</b>	c0=2 c1=2 c2=3 c3=3 c4=3 c5=5	c0=W c1=W/cnt c2=W/cnt <sup>2</sup> c3=W/cnt <sup>3</sup> c4=W/cnt <sup>4</sup> c5=W/cnt <sup>5</sup>	6	1	1	integer2	2	12	200
<b>Size of the record</b>										212

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FIELD	DESCRIPTION	SF	UNITS	DIM1	DIM2	DIM3	TYPE	TYPE SIZE	FIELD SIZE	OFFSET
RECORD_HEADER	Generic Record Header	0		1	1	1	REC_HEAD	20	20	0
	<b>GENERIC QUALITY INDICATORS</b>									
DEGRADED_INST_MDR	Quality of MDR has been degraded from nominal due to an instrument degradation	0	NA	1	1	1	boolean	1	1	20
DEGRADED_PROC_MDR	Quality of MDR has been degraded from nominal due to a processing degradation	0	NA	1	1	1	boolean	1	1	21
<b>Scan Line Information</b>										
LINE_COUNTER	Line counter since last auto-calibration sequence. If calibration enabled then it runs from 0 to 39 else from 0 to 8191 followed by 0 to 8191 and so on	0	NA	1	1	1	u-integer2	2	2	22
SCAN_TYPE_CODE	Scan type code (0 = Earth view, 1 = space view, 2 = cold BB view, 3 = warm BB view, 4 = else.	0	NA	1	1	1	u-integer2	2	2	24
QUALITY_INDICATOR	Quality Indicator Bit Field	0	N/A	1	1	1	bitst(32)	4	4	26
SCAN_LINE_QUALITY	Scan Line Quality Flags	0	N/A	1	1	1	bitst(32)	4	4	30
DATA_CALIBRATION	Noise-Equivalent Delta N and Channel Quality Flags	0	N/A	20	1	1	DATA_CALQUAL	2	40	34
<b>MEASUREMENT DATA</b>										
DIGITAL_A_DATA_ELEMENT_COUNT	The 56 elements contain the 56 pixel values of a scan line in the 20 channels	0	NA	56	1	1	DATA_ELEM_CO UNT	44	2464	74
DIGITAL_A_DATA_ELEMENT_FLAG	The 8 elements contain information on the instrument status	0	NA	8	1	1	DATA_ELEM_FL G	44	352	2538
<b>Digital B telemetry</b>										
INSTRUMENT_INVALID_DIGITAL_WORD_FLAG	Invalid Word Bit Flags	0	N/A	1	1	1	bitst(16)	2	2	2890
DIGITAL_B_DATA	Digital B Data	0	N/A	1	1	1	bitst(16)	2	2	2892
<b>Analog telemetry</b>										

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<b>INSTRUMENT_INVALID_ANALOG_WORD_FLAG</b>	Invalid Word Bit Flags	0	N/A	1	1	1	bitst(32)	4	4	2894
<b>ANALOG_DATA</b>	Analog Data	0	N/A	16	1	1	u-byte	1	16	2898
<b>NAVIGATION DATA AT SCAN LINE</b>										
<b>TIME_ATTITUDE</b>	Time Associated with Attitude Angles	0	s	1	1	1	u-integer4	4	4	2914
<b>EULER_ANGLE</b>	Euler Angles: Roll, Pitch, Yaw	3	deg	3	1	1	integer2	2	6	2918
<b>NAVIGATION_STATUS</b>	Navigation Status Bit Field	0	N/A	1	1	1	bitst(32)	4	4	2924
<b>SPACECRAFT_ALTITUDE</b>	Spacecraft Altitude Above Reference Geoid (MSL)	1	km	1	1	1	u-integer4	4	4	2928
<b>ANGULAR_RELATION</b>	Angular relationships: solar zenith angle, satellite zenith angle, solar azimuth angle, satellite azimuth angle (FOV 1 to 56). Note: azimuth angle range is -180 to +180, where minus is west and plus is east.	2	deg	4	56	1	integer2	2	448	2932
<b>EARTH_LOCATION</b>	Earth Location: latitude, longitude (FOV 1 to 56)	4	deg	2	56	1	integer4	4	448	3380
<b>SURFACE_PROPERTY</b>	Surface property (0 = water, 1 = mixed/coast, 2 = land)			56	1	1	integer2	2	112	3828
<b>TERRAIN_ELEVATION</b>	Average terrain elevation (FOV 1 to 56)		m	56	1	1	integer2	2	112	3940
<b>Calibration Coefficient (see Section 3.5.1.12)</b>										
<b>PRIMARY_CALIBRATION_SECOND_TERM</b>	Primary Calibration Second Order Term a2 (ch. 1-20)	12	$\dagger$ mW/m <sup>2</sup> /sr/cm <sup>-1</sup> /cnt <sup>2</sup> or % alb/cnt <sup>2</sup> (ch 20)	20	1	1	integer4	4	80	4052
<b>PRIMARY_CALIBRATION_FIRST_TERM</b>	Primary Calibration First Order Term a1 (ch. 1-20)	9	$\dagger$ mW/m <sup>2</sup> /sr/cm <sup>-1</sup> /cnt or % alb/cnt (ch 20)	20	1	1	integer4	4	80	4132
<b>PRIMARY_CALIBRATION_ZEROTH_TERM</b>	Primary Calibration Zeroth Order Term a0 (ch. 1-20)	6	$\dagger$ mW/m <sup>2</sup> /sr/cm <sup>-1</sup> or % alb (ch 20)	20	1	1	integer4	4	80	4212
<b>SPARE_CALIBRATION_SECOND_TERM</b>	Spare Calibration Second Order Term (ch. 1-20)	12	$\dagger$ mW/m <sup>2</sup> /sr/cm <sup>-1</sup> /cnt <sup>2</sup> or % alb/cnt <sup>2</sup> (ch 20)	20	1	1	integer4	4	80	4292

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<b>SPARE_CALIBRATION_FIRST_TERM</b>	Spare Calibration First Order Term (ch. 1-20)	9	†mW/m <sup>2</sup> /sr/c m <sup>-1</sup> /cnt or % alb/cnt (ch 20)	20	1	1	integer4	4	80	4372
<b>SPARE_CALIBRATION_ZEROTH_TERM</b>	Spare Calibration Zeroth Order Term(ch. 1-20)	6	†mW/m <sup>2</sup> /sr/c m <sup>-1</sup> or % alb (ch 20)	20	1	1	integer4	4	80	4452
<b>CLOUD COVERAGE INFORMATION</b>										
<b>PERCENTAGE_CLEAR_SKY</b>	Percentage of sky that is clear of clouds	2	%	56	1	1	u-integer2	2	112	4532
<b>SIZE OF THE MDR</b>										4644

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FIELD	DESCRIPTION	SF	UNITS	DIM1	DIM2	DIM3	TYPE	TYPE SIZE	FIELD SIZE	OFFSET
RECORD_HEADER	Generic Record Header	0		1	1	1	REC_HEAD	20	20	0
	<b>GENERIC QUALITY INDICATORS</b>									
DEGRADED_INST_MDR	Quality of MDR has been degraded from nominal due to an instrument degradation	0	NA	1	1	1	boolean	1	1	20
DEGRADED_PROC_MDR	Quality of MDR has been degraded from nominal due to a processing degradation	0	NA	1	1	1	boolean	1	1	21
<b>Scan Line Information</b>										
LINE_COUNTER	Line counter since last auto-calibration sequence. If calibration enabled then it runs from 0 to 39 else from 0 to 8191 followed by 0 to 8191 and so on	0	NA	1	1	1	u-integer2	2	2	22
SCAN_TYPE_CODE	Scan type code (0 = Earth view, 1 = space view, 2 = cold BB view, 3 = warm BB view, 4 = else.	0	NA	1	1	1	u-integer2	2	2	24
QUALITY_INDICATOR	Quality Indicator Bit Field	0	N/A	1	1	1	bitst(32)	4	4	26
SCAN_LINE_QUALITY	Scan Line Quality Flags	0	N/A	1	1	1	bitst(32)	4	4	30
DATA_CALIBRATION	Noise-Equivalent Delta N and Channel Quality Flags	0	N/A	20	1	1	DATA_CALQUAL	2	40	34
<b>MEASUREMENT DATA</b>										
DIGITAL_A_DATA_ELEMENT_RAD	Radiances for 56 pixel values of a scan line in the 20 channels. Earth scan pixel values are calibrated to radiances (channel 1 - 19) and reflectance factors (channel 20)	4	NA	56	1	1	DATA_ELEM_RA D	84	4704	74
DIGITAL_A_DATA_ELEMENT_FLAG	Information on the instrument status.	0	NA	8	1	1	DATA_ELEM_FL AG	44	352	4778
<b>Digital B telemetry</b>										
INSTRUMENT_INVALID_DIGITAL_WORD_FLAG	Invalid Word Bit Flags	0	N/A	1	1	1	bitst(16)	2	2	5130
DIGITAL_B_DATA	Digital B Data	0	N/A	1	1	1	bitst(16)	2	2	5132
<b>Analog telemetry</b>										



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<b>INSTRUMENT_INVALID_ANALOG_WORD_FLAG</b>	Invalid Word Bit Flags	0	N/A	1	1	1	bitst(32)	4	4	5134
<b>ANALOG_DATA</b>	Analog Data	0	N/A	16	1	1	u-byte	1	16	5138
<b>NAVIGATION DATA AT SCAN LINE</b>										
<b>TIME_ATTITUDE</b>	Time Associated with Attitude Angles	0	s	1	1	1	u-integer4	4	4	5154
<b>EULER_ANGLE</b>	Euler Angles: Roll, Pitch, Yaw	3	deg	3	1	1	integer2	2	6	5158
<b>NAVIGATION_STATUS</b>	Navigation Status Bit Field	0	N/A	1	1	1	bitst(32)	4	4	5164
<b>SPACECRAFT_ALTITUDE</b>	Spacecraft Altitude Above Reference Geoid (MSL)	1	km	1	1	1	u-integer4	4	4	5168
<b>ANGULAR_RELATION</b>	Angular relationships: solar zenith angle, satellite zenith angle, solar azimuth angle, satellite azimuth angle (FOV 1 to 56) Note: azimuth angle range is -180 to +180, where minus is west and plus is east.	2	deg	4	56	1	integer2	2	448	5172
<b>EARTH_LOCATION</b>	Earth Location: latitude, longitude (FOV 1 to 56)	4	deg	2	56	1	integer4	4	448	5620
<b>SURFACE_PROPERTY</b>	Surface property (0 = water, 1 = mixed/coast, 2 = land)			56	1	1	integer2	2	112	6068
<b>TERRAIN_ELEVATION</b>	Average terrain elevation (FOV 1 to 56)		m	56	1	1	integer2	2	112	6180
<b>Calibration Coefficient (see Section 3.5.1.12)</b>										
<b>PRIMARY_CALIBRATION_SECOND_TERM</b>	Primary Calibration Second Order Term a2 (ch. 1-20)	12	$\uparrow$ mW/m <sup>2</sup> /sr/cm <sup>-1</sup> /cnt <sup>2</sup> or % alb/cnt <sup>2</sup> (ch 20)	20	1	1	integer4	4	80	6292
<b>PRIMARY_CALIBRATION_FIRST_TERM</b>	Primary Calibration First Order Term a1 (ch. 1-20)	9	$\uparrow$ mW/m <sup>2</sup> /sr/cm <sup>-1</sup> /cnt or % alb/cnt (ch 20)	20	1	1	integer4	4	80	6372
<b>PRIMARY_CALIBRATION_ZEROTH_TERM</b>	Primary Calibration Zeroth Order Term a0 (ch. 1-20)	6	$\uparrow$ mW/m <sup>2</sup> /sr/cm <sup>-1</sup> or % alb (ch 20)	20	1	1	integer4	4	80	6452

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<b>SPARE_CALIBRATION_SECOND_TERM</b>	Spare Calibration Second Order Term (ch. 1-20)	12	†mW/m <sup>2</sup> /sr/ cm <sup>-1</sup> /cnt <sup>2</sup> or % alb/cnt <sup>2</sup> (ch 20)	20	1	1	integer4	4	80	6532
<b>SPARE_CALIBRATION_FIRST_TERM</b>	Spare Calibration First Order Term (ch. 1-20)	9	†mW/m <sup>2</sup> /sr/ cm <sup>-1</sup> /cnt or % alb/cnt (ch 20)	20	1	1	integer4	4	80	6612
<b>SPARE_CALIBRATION_ZEROTH_TERM</b>	Spare Calibration Zeroth Order Term(ch. 1-20)	6	†mW/m <sup>2</sup> /sr/ cm <sup>-1</sup> or % alb (ch 20)	20	1	1	integer4	4	80	6692
<b>CLOUD COVERAGE INFORMATION</b>										
<b>PERCENTAGE_CLEAR_SKY</b>	Percentage of sky that is clear of clouds	2	%	56	1	1	u-integer2	2	112	6772
<b>SIZE OF THE MDR</b>										<b>6884</b>

Field Type	Size in Bytes
bitst(8)	1
boolean	1
byte	1
char(1)	1
e-char(1)	1
enumerated	1
u-byte	1
bitst(16)	2
char(2)	2
DATA_CALQUAL	2
e-char(2)	2
integer2	2
u-integer2	2
bitst(24)	3
char(3)	3
e-char(3)	3
bitst(32)	4
char(4)	4
integer4	4
u-integer4	4
short cds time	6
integer8	8
long cds time	8
u-integer8	8
general time	15
REC_HEAD	20
DATA_ELEM_COUNT	44
DATA_ELEM_FLAG	44
DATA_ELEM_RAD	84
char(88)	88

NOTE: Table must be sorted into ascending order